



## AI Testbed framework for composable behaviour representation

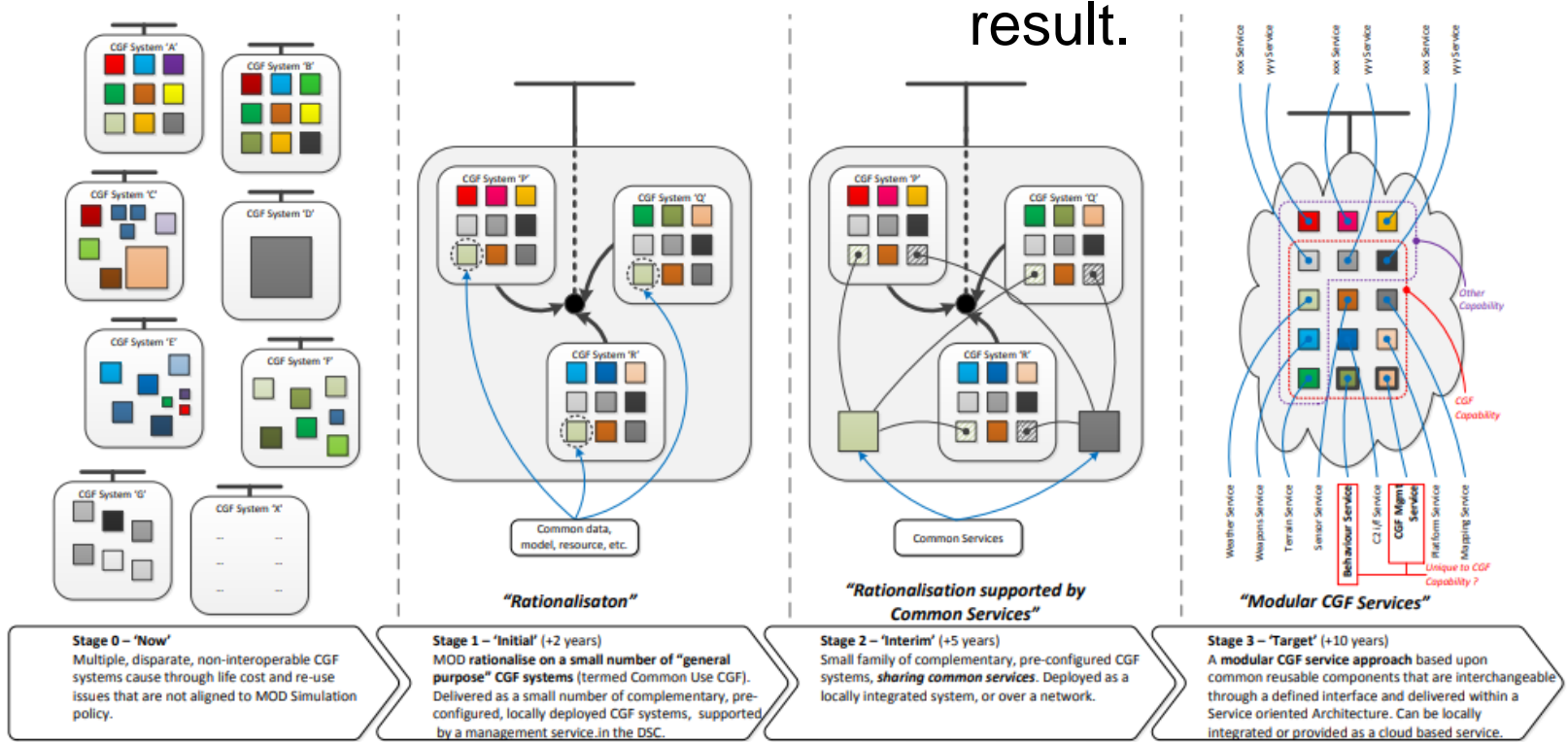
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# So what's the problem?

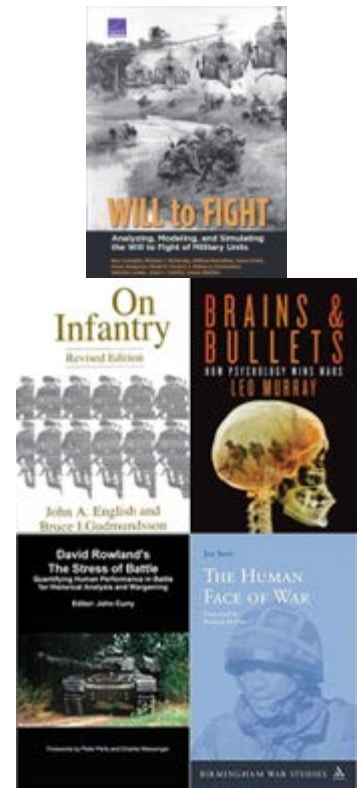
- No single Computer Generated Force (CGF) represents the full breadth of behaviours that occur in operational environments.
- Often, multiple CGFs need to be utilised which creates interoperability challenges and may result in limited and redundant functionality as a result.



- How can we better understand approaches for the development of common simulation components for modelling Computer Generated Forces (CGF) Behaviours?
- First step was to develop an AI testbed which could be used to investigate novel approaches to behavioural representation in military simulations
- This will later allow us to test theoretical work previously conducted into the development of composable behaviours.

## Combat Participation / Will to Fight test case

- Inspired by RAND Will to Fight study\*
- Based on existing Dstl Historical Analysis material (David Rowland, Jim Storr, Dermot Rooney etc)
- Effect hard to quantify but vital to represent manoeuvre warfare
- Under represented in many military training simulations, but available in some commercial games



- Tabletop Wargame
  - City level urban combat in Grozny 1994/5 with platoon level forces.
- COTS Computer Simulation
  - Combat Mission: Shock Force 2. Street level urban combat in modern Syria with section level forces.
  - Perception of events by a CGF is key to representing these factors
- Excel Model
  - Created an Excel based “Close Combat Participation Model” (CCPM) analysis tool
- Conclusions
  - Suppression and flanking are poorly characterised parameters, especially in constrained environments.



- [“Hacking into the Combat AI of Watch Dogs 2”\\*](#)
- Basic Logic of reaction to contact
  - **First Cover:** Initial Reaction to Contact
  - **Neighbouring Cover:** Shoot and Move
  - **Second Cover:** Gain a Tactical Advantage

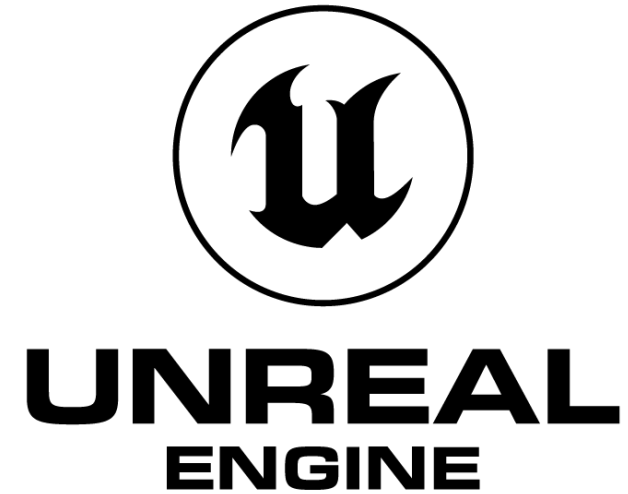


- Search Criteria
  - Distance to target
  - Distance to Move
  - Angle to Target
  - *Line of sight*

	Distance to Target	Distance to Move	Protection	Line of Sight
First Cover	Medium	High	Low	No
Neighbouring Cover	High	Medium	Low	Yes
Second Cover	High	Medium	Medium	Yes

\*Dickie-Clarke, C. (2018). *Hacking into the Combat AI of Watch Dogs 2*. [online] [www.youtube.com](https://www.youtube.com/watch?v=c06DZ81TbmK). Available at: <https://www.youtube.com/watch?v=c06DZ81TbmK> [Accessed 16 Sep. 2021].

- Unreal 4 Based
- Plugin based design
- Support for dismounted close combat entities including:
  - Tasks
  - Stances
  - Formations
  - Factions
- Utilisation of existing UE4 Capabilities

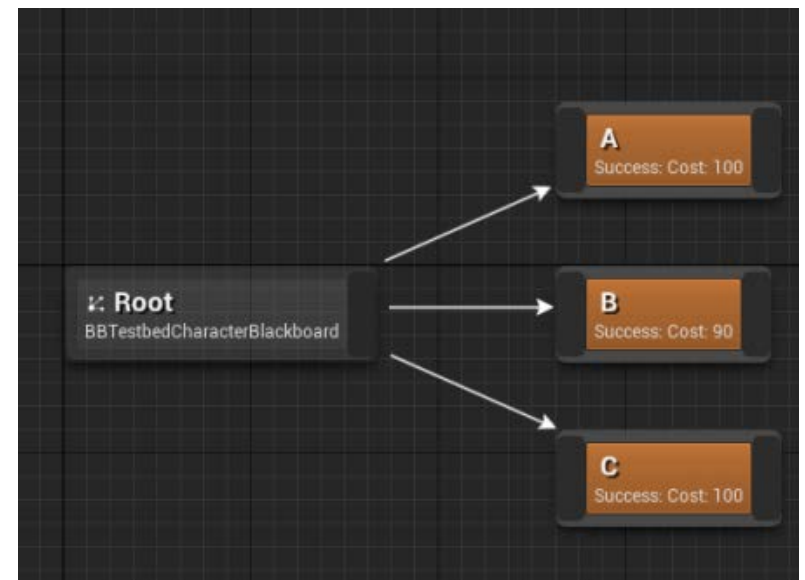
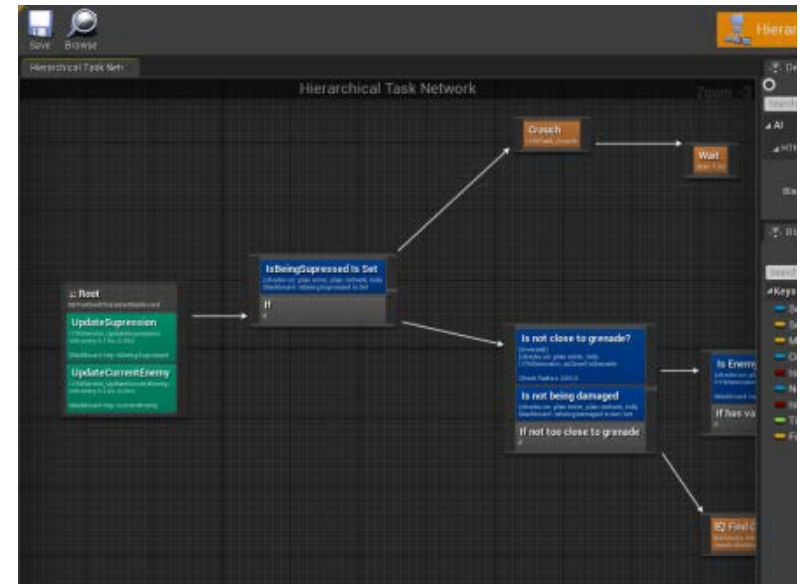


- Sense
  - Perception Components
  - Environmental Query System (EQS)
- Think
  - Blackboard
  - ~~Behaviour Trees~~ (more on this in a minute)
- Act
  - Navigation Mesh

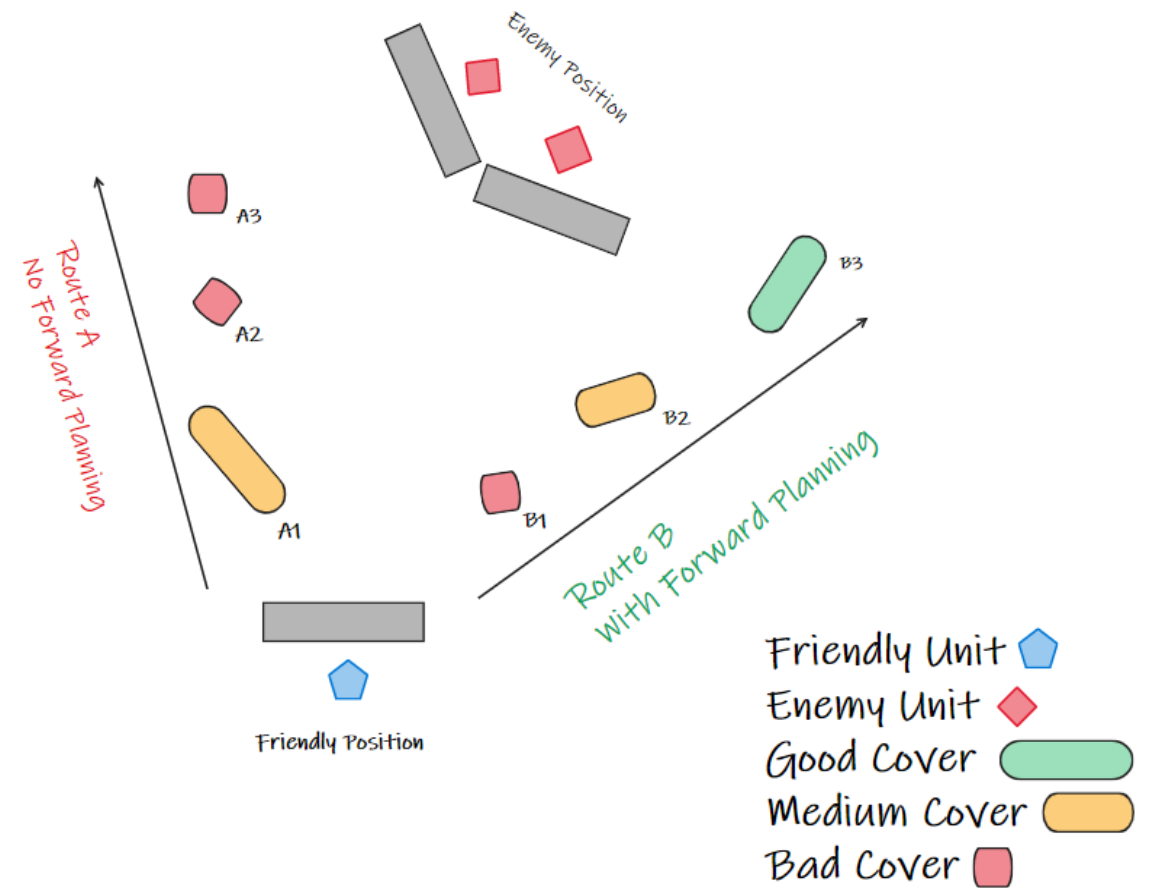




- Core AI Logic
- Multiple 'plans' can be explored before choosing the preferred course of action
- Combining Planning and a Tree structure together allows multiple styles of AI programming depending on complexity/performance requirements



- The Unreal Engine supports the 'Sense, Think, Act' paradigm.
- Behaviour Trees are limited to choosing a single course of action
- The replacement with a HTN has enabled Forward Planning which in turn allows more realistic and complex behaviours to be authored



- UE4 is a good candidate for an AI testbed
- Team-based support adds significant complexity
- The time to author behaviours is significant
- Combat Participation or “Will to Fight” is a core concept that should be built into an AI framework from the outset.
- Developing a runtime editing capability is a key addition for longer-term use.

## Tools

- Continue to monitor commercial games developments
- Continue exploration of Unreal Engine capabilities to support other prototyping tasks.

## Behaviours

- Encode sample UK Battle Drills as HTN's to stress the framework.
- Explore how Will-to-Fight can be applied at other scales of simulation (Section, Company, Brigade)
- Develop an understanding of the behavioural information that must be passed between simulation components.

## Path's to exploitation



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Questions?

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